

Saturday, January 23, 2016

animation proof

i created animation in algodoo and it works!

quick view of my gear...soon i will have all parts :) stay tuned



almost finished ;)

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RoX

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▼ 2016 (2)

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[animation proof](#)

[reproduction - part 1](#)

► 2015 (8)

Posted by RoX at 2:36 PM No comments:

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Friday, January 8, 2016

reproduction - part 1

first part of ermola device which makes motor to spin...

<https://www.youtube.com/watch?v=QqmUgWnzk6w>



Posted by RoX at 11:54 AM No comments:

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Thursday, December 31, 2015

replication

Now i am trying to replicate this motor with all schemes, images, videos and patents what i find online.

Images and videos of my model coming soon...

contact me here: [surf2rok](#)

Posted by RoX at 4:28 AM No comments:

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patent

The patent of this motor.

[first](#) in word

[second](#) in pdf

the [NEW](#) with chain

Posted by RoX at [4:23 AM](#) No comments:



animations

How motor works in 3D animation.

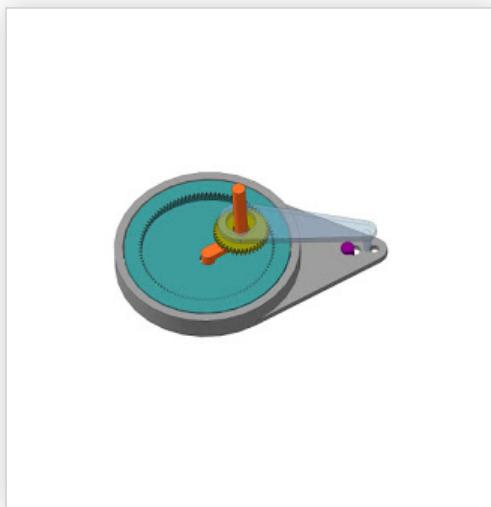


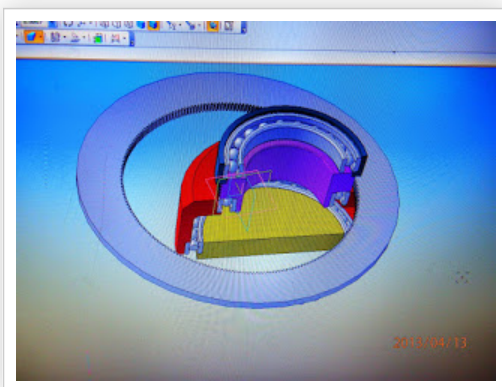
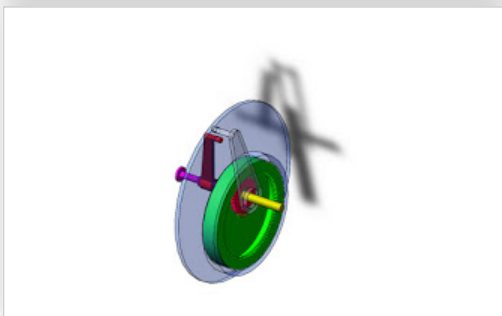
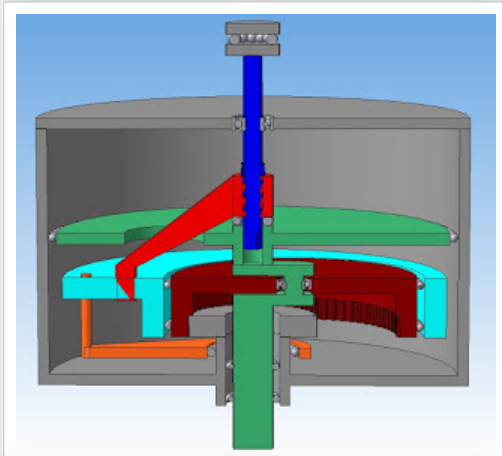
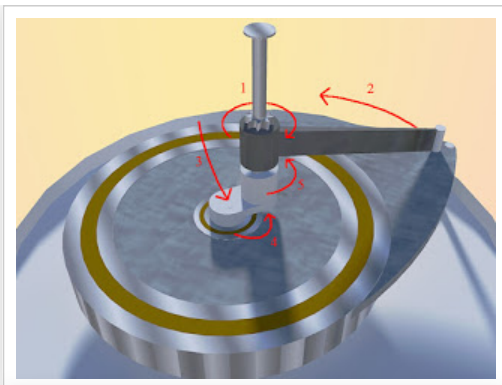
Posted by RoX at [4:14 AM](#) No comments:



3D gallery

Some 3D images of the motor.



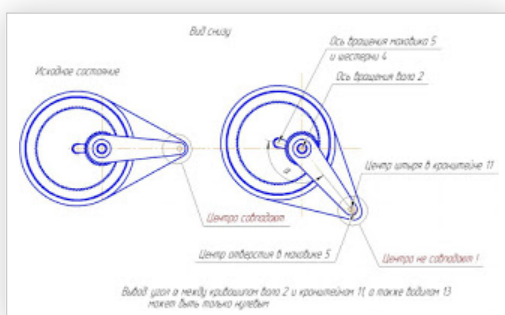
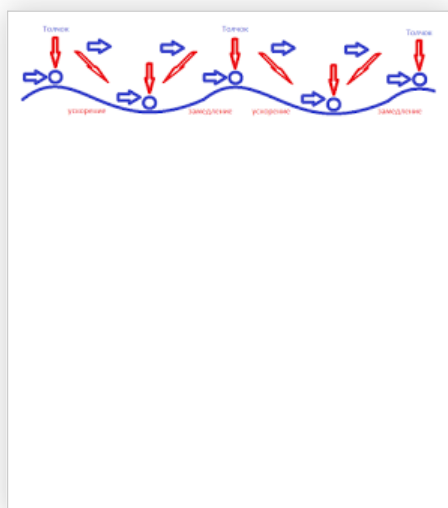
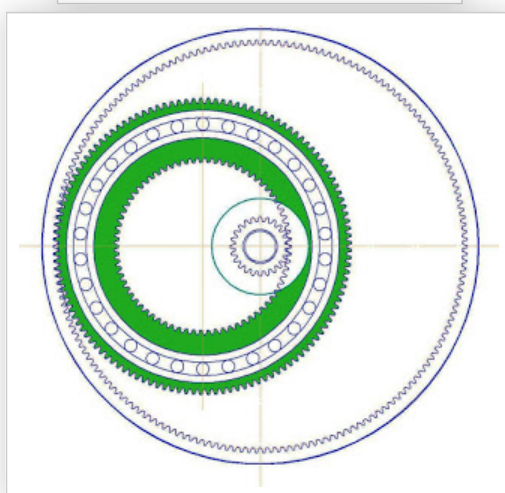
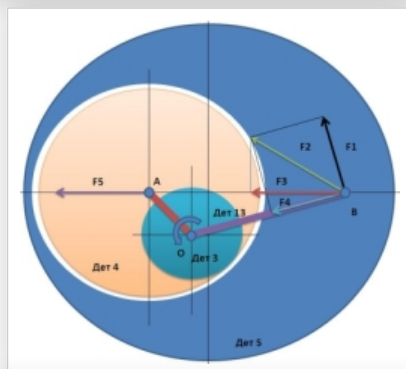
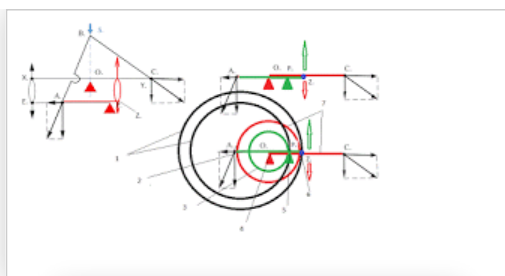


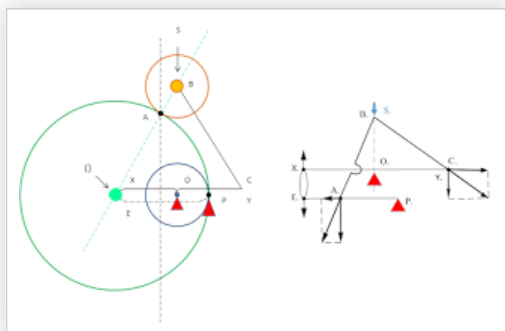
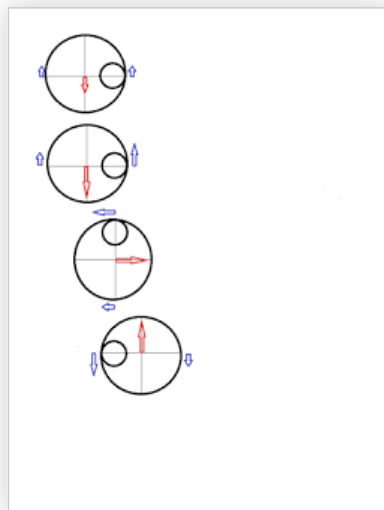
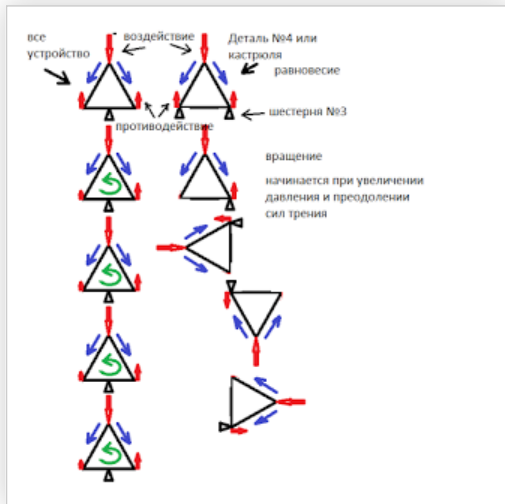
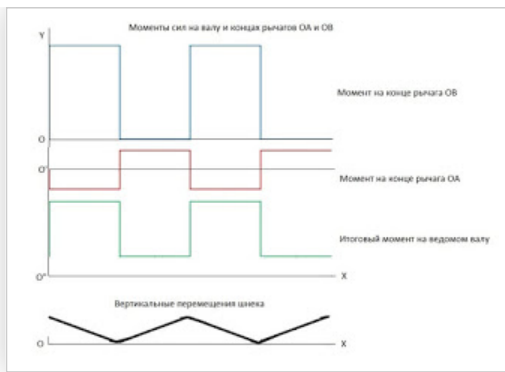
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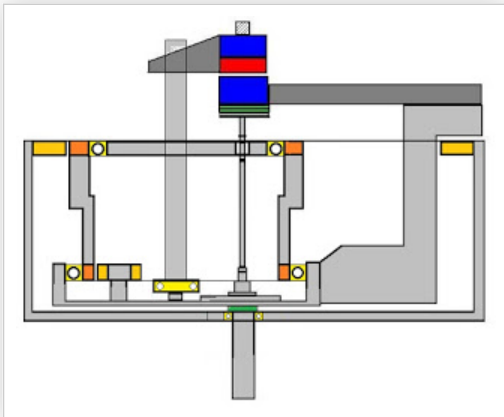
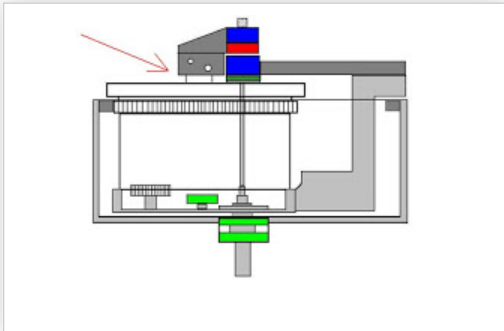
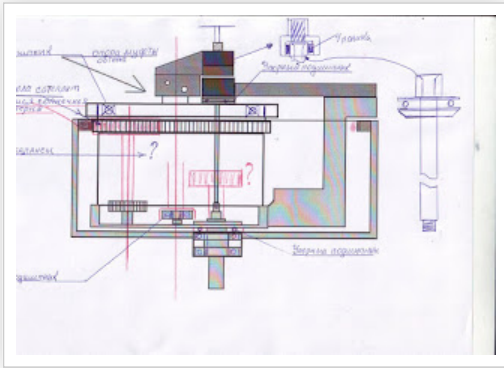
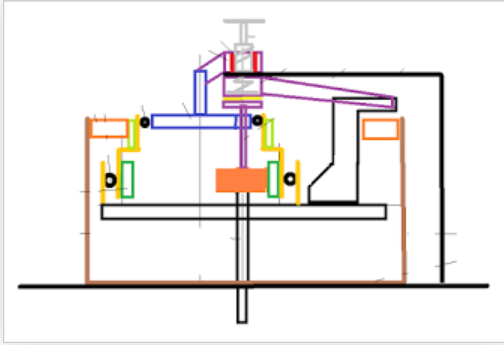
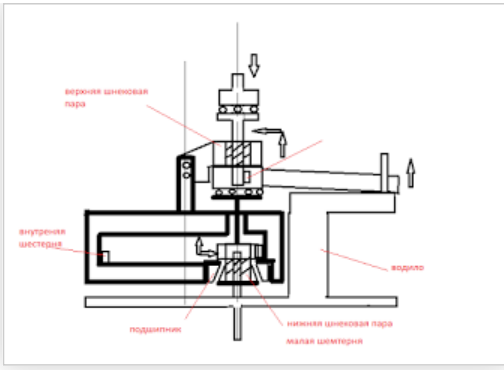
schemes

All schemes about how the energy is converted and the motor is spinning.



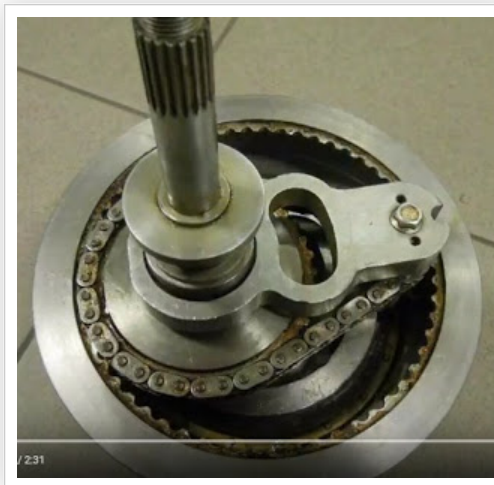


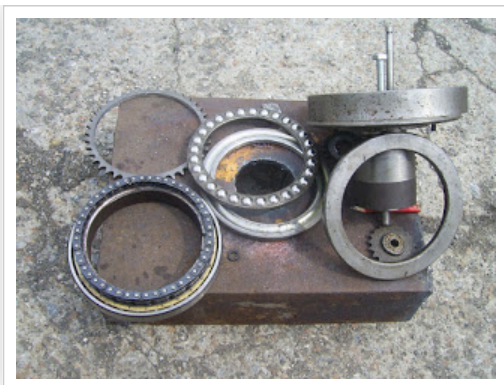
And some theories how the motor looks inside.



new motor

Recently i find images of new model which include chains. I think it's less noisy and more efficient.





Posted by [RoX](#) at [3:58 AM](#) [No comments:](#)

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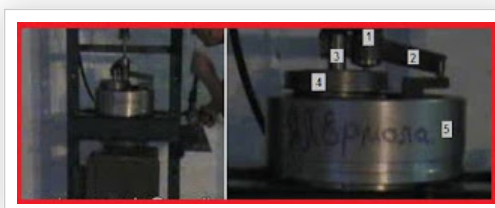
old motor

I think this are the images of the first prototype of this motor.









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the beginning

Hi,

I research everything about **Andrey Ermola** (ЕРМОЛА АНДРЕЙ) motor called **perpetuum mobile**.

It works on converting potential to kinetic energy with gears.

Here is official website ermola.com.ua and [youtube](#) channel.

Images and videos in next posts...

The proof of the theorem:

"... If we take $\triangle ABC$ and put emphasis on the point O., putting effort into the top of B. S. aimed at O., then $\triangle ABC$ not provernetsya (Figure 1).

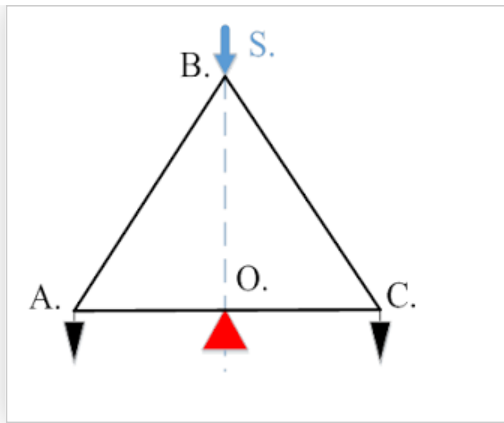


Fig. 1

Since the applied force S in $\angle V.A.S. = \angle V.S.A.$ But if the force S in $\angle V.A.S. \geq \angle V.S.A.$, then Δ may provernetsya ($\geq$ sign read as more and the same). Thereby recognizing that perpetual motion is possible. After 26 years, the Paris Academy of Sciences forbidden to accept and consider applications for perpetual motion, arguing that this simply could not and can not be referring to the findings of their own "scientists". **There is a unique way to make S effort into the top of B .** Thus aimed at $\angle V.A.S. \geq \angle V.S.A.$ (Figure 2).

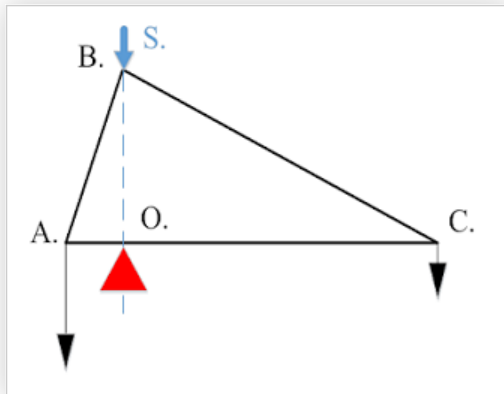


Fig. 2

But Δ is not turned.

How to solve this problem?

The solution is simple - on the not isosceles ΔABC we put the effort into the top of B . S aimed at Thus, where there are forces at the vertices A and C (Figure 2). To cranked triangle, remove the emphasis of the TS (Figure 2), but to create a force at the top of A . are putting into the middle of the lever ER , which m . R . is the palm, the force at the top of C . m . Y . arm $X.Y$. in the middle of which stands the focus of the TS axis (Figure 3).

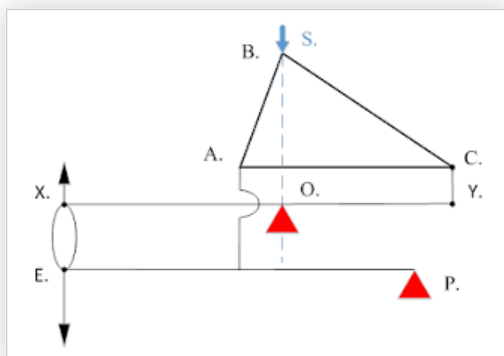


Fig. 3

Leverage ER and $X.Y$. not rigidly linked to t . X ., and so on. E .

application of force on the lever of the vertex A . ER It creates a force in tons. E . half cranks and downwards. A force is applied to the top of the lever C . $X.Y$. transmit the same effort in t . X . and will, tends to prevail. Interconnected levers t . X . and so on. E . TURNED BY ΔABC , as a force of tonnes. $> E$. t . X .

The question arises? At some point, it is necessary to apply a force S . Δ to Δ was at rest (not turned)?

Even if an effort is not t. G. and applying closer towards the vertex C Δ vseravno will rotate, until until the force at the top of A. will be more twice than the top of the C, then comes the rest state (Figure 4).

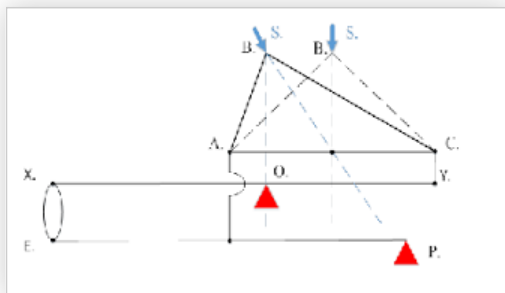


Fig. 4

With Andrei Dmitrievich, we have constructed a working model. I accompanied the project as an inventor, and all the technical part lay on Sakharov.

Establish mechanisms for nodes, in other words, how to do better and easier. I consented, choosing the best and most acceptable, not counting the whole project once again. And here it is - my day of triumph has come, but, alas, to my great regret, the mechanism worked in the "wedge". The first three days were trying to run through (sticking) could not get run. There were many days, weeks, months, and only after more than half a year, calculated on the paper and laid on the design of the vector and the leverage realized overdone. Eureka! The wedge design is inevitable, as long as there is no Δ . You lose the vector AS (ris5). The forces are equal, Ivan Artobolevsky.

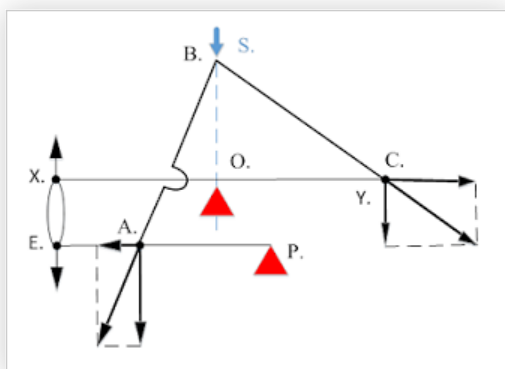


Fig. 5

In this article, I have shown and described the principle of operation of my machine. Dilettante and swindlers please do not disturb.

For all those who have tried and tries to construct a similar model, good luck and victory.

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